Selection Form	Lifter(Elevato	r)		Requested Date:			
Please check "✓" the corres	ponding item in $\Box$ . If	you are unable to m	nake a selection, plea	ase leave it blank.			
Select Series and Backlas	sh of High Precision Re	ducer for Servo Mo	tor				
<del>.</del>	rallel Shaft • Planetary Type (		act Hollow Shaft Type (AF		d Shaft Type (AFC)		
Backlash   □ 3 arcmin	15 arcmin	└ ∐ 3;	arcmin 30 arcmin	☐ 3 arcmin	30 arcmin		
Series   → Hollow Shaft		I Shaft Type (AF3)	Parallel Shaft Type		t Angle Shaft (AH2)		
		1 arcmin 3 arcmin		└ Low Backlash └ Low Backlash			
Low Back			·	rcmin) accuracy would be different by reduction ratio.			
Requested M	1odel ( 	) *1	f you already know the mode	el number, please enter that in	( ).		
		<u>N</u>	<u>и</u> м4 м5		Sample Image		
User Condition							
Elevating Speed	V =	mm/s	P.C.D. of Driven Side S		mm		
<ul><li>Weight of the Work</li></ul>	M1=	kg	(Timing Pulley, Gear)  P.C.D. of Drive Side Sp	* Not required for direct corocket D5 =	oupling mm		
Weight of the Work	WII —		•	* Not required for direct of			
<ul> <li>Weight of the Balancing W</li> </ul>	/eight M2=	kg	Friction Coefficient of	the Bearing $\mu =$			
<ul><li>Weight of the Chain (Wire)</li></ul>	) M3 =	kg	Rated Rotational Spee	d of Servo Motor N1 =	r/min		
Weight of the Sprocket (Ti	ming Pulley) M4=	kg	Other User Condition				
<ul> <li>Weight of the Rotating Sha</li> </ul>	aft M5=	kg					
P.C.D. of the Sprocket (Time)	ning Pulley) D1=	mm					
<ul> <li>Pitch Circle Diameter of the Element Bearing</li> </ul>	e Rolling D2=	mm					
Outer Diameter of the Rota	ating Shaft D3 =	mm					
■ Driving Pattern and Cond	dition						
<b>←</b>	〒F夕□土 パク > 1	1 サイクル 1Cycle	- 14 II + 1° 1° 1° 1° 1° 1° 1° 1° 1° 1° 1° 1° 1°	日吐パケ こう て 下降の	→ ・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・		
					ing Pattern 3		
Y2Dead (r/min) Input Motor Speed (r/min) Input Motor Speed (r/min) It 1 t2 t3 t4 Ascending Pattern 1	50 45 t6 t7	8 t9 t10	변화 보기	t14 t15 t16 t1	型 Fill Time (sec.)		
	t1 = sec.		Acceleration Time 2	t4 = sec.			
Constant Speed Time 1 t	t2 = sec.		Constant Speed Time 2	t5 = sec.			
Deceleration Time 1 t	t3 = sec.		Deceleration Time 2	t6 = sec.			
	11 -  / -   ./	(Enter Average	Enter Rotational Speed	n4 = n5/2 r/m			
(Acceleration) 1 Enter Rotational Speed n	n2 = r/min	Rotational Speed)	(Acceleration) 2 Enter Rotational Speed	n5 = r/m	Rotational Speed) in		
(Constant Speed) 1		(Enter Average	(Constant Speed) 2 Enter Rotational Speed				
(Deceleration) 1	15 —  , =   1/111111	Rotational Speed)	(Deceleration) 2	n6 =	Rotational Speed)		

Acceleration Time 3  Constant Speed Time 3  Deceleration Time 3	t7 =							
·		sec.		Acceleration Time 4	t10 =		sec.	
Deceleration Time 3	t8 =	sec.		Constant Speed Time 4	t11=		sec.	
	t9 =	sec.		Deceleration Time 4	t12 =		sec.	
Enter Rotational Speed (Acceleration) 3	n7 = n8/2	r/min	(Enter Average Rotational Speed)	Enter Rotational Speed (Acceleration) 4	n10=	n11/2	r/min	(Enter Average Rotational Speed)
Enter Rotational Speed (Constant Speed) 3	n8 =	r/min		Enter Rotational Speed (Constant Speed) 4	n11=		r/min	, ,
Enter Rotational Speed (Deceleration) 3	n9 = n8/2	r/min	(Enter Average Rotational Speed)	Enter Rotational Speed (Deceleration) 4	n12 =	n11/2	r/min	(Enter Average Rotational Speed)
,				,				
<ul><li>Ascending Pattern 3</li></ul>				<ul><li>Descending Patter</li></ul>			ī	
	t13 =	sec.		Acceleration Time 6	t16=		sec.	
Constant Speed Time 5	t14=	sec.		Constant Speed Time 6	t17 =		sec.	
Deceleration Time 5	t15 =	sec.		Deceleration Time 6	t18=		sec.	
Enter Rotational Speed (Acceleration) 5	n13 = n14/	r/min	(Enter Average Rotational Speed)	Enter Rotational Speed (Acceleration) 6	n16 =	n17/2	r/min	(Enter Average Rotational Speed)
Enter Rotational Speed	n14 =	r/min	notational opeca,	Enter Rotational Speed	n17 =		r/min	notational opeca,
(Constant Speed) 5 Enter Rotational Speed	n15 = n14/2	r/min	(Enter Average	(Constant Speed) 6 Enter Rotational Speed	n18=	n17/2	r/min	(Enter Average
(Deceleration) 5	1113 — 1114/	1/111111	Rotational Speed)	(Deceleration) 6	1119 —	1117/2	] 17111111	Rotational Speed)
	o Use ∗If you	ı planned to	use specific Sevo I	Viotor, please write here. (Model	Series			nical Support Desk
Planned Servo Motor to	o Use ∗If you	ı planned to	use specific Sevo I	Motor, please write here. (Model	Series	CS cen	ter Tech	nical Support Desk cs@nissei-gtr.co.jp
	o Use ∗Ifyou	ı planned to	use specific Sevo I	Motor, please write here. (Model	Series	CS cen	ter Tech	• • •
Customer Information	o Use ∗If you	ı planned to	use specific Sevo I		Series	CS cen	ter Tech	• • •
Customer Information	o Use *If you	ı planned to	use specific Sevo I		Series	CS cen	ter Tech	• • •
Customer Information  Company Name  Department	o Use ∗If you	ı planned to	use specific Sevo I	Address	Series	CS cen	ter Tech	• • •
Customer Information  Company Name  Department  Job Title	O Use *If you	ı planned to	use specific Sevo I	Address  Phone Number	Series	CS cen	ter Tech	• • •
Customer Information  Company Name  Department  Job Title  Name	O Use *If you	planned to		Address  Phone Number  FAX Number	Series	CS cen E-mail	ter Tech	• • •
Customer Information  Company Name  Department  Job Title  Name  Purpose of Selection				Address  Phone Number  FAX Number  E-mail  ange model		CS cen E-mail	ter Tech-	• • •
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**NISSEI CORPORATION** 

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